Technical Features

- Type: Continuous Mill of 18 mill stands, an outlet to cooling bed and bar evacuation The mill is composed of:

 - 1 Heating furnace of 80 Tr/h 6 Roughing mill stands 3H & 3V 6 Intermediate mill stands 3H & 3V
 - 6 Finishing stands 5H & 1V
 - **Cutting shears**
 - Outlet roller table, cooling bed and bar evacuation system
 - Wire rod block, laving forming device, lay cooling R.T. and coil carroussel handling.
- Incoming material: square billets
 - SECTION: 120 x 120 ÷ 160 x 160 mm
 - LENGTH: 6.000 mm ÷12.000 mm
- Finished product:
 - Rar

8 to 32 mm, diameter

Wire rod:

5.5 to 14 mm

- Product length:
 - Rebars (corrugated):

Wire rod:

6 ÷ 12 m 2,3ton max

- Product speed:
 - Bar

14 m/sg

Wire rod:

80 m/sg (5,5mm)



Main Control Pulpit

Electrical Process Description

- The electric and automation equipment to be installed in said plant, includes the following main sections:
 - 22/0,4 kV Indoor Electrical Substation, power distribution and power factor correction at 20 kV.
 - AC and DC equipment, drive equipment with corresponding motors, digital technology DC thyristor converters for the mill stands and shears main drives. AC/AC converters for variable speed auxiliary drives.
 - Automation Systems: Control PLC's, remote I/O units, HMI operator stations, control desks.
 - Auxiliary equipment: field sensors, etc.
- The Integrated Control System topology is configured as a flexible distributed control incorporating PLC's, I/O's remote units, operator stations and HMI displays, interfaced through an industrial TCP-IP Ethernet network of 100 Mb/s and local networks type INTERBUS, PROFIBUS, etc.

The control systems incorporate state-of-the-art Pentium processing units with high dynamic response designed to suite the process requirements.

The master speed control system (master mill) is a dedicated PLC that calculates the speed references for each one of the continuous rolling milf's drives (stands, pinch-roll, shears, roller tables, etc). This system executes the following main control functions:

- Speed reference for stands / other motors
- Minimum voltage between Rolling Mill Stands
- Regulation of loop position between stands
- Impact speed reference
- Speed reference in jogging mode (slow)
- Master speed reference
- Speed adjustments in simple or cascade mode
- Continuity control between stands
- Control of dummy bar (testing)
- Elaboration of cutting commands (trimmings, cut to
- **Cut optimization**